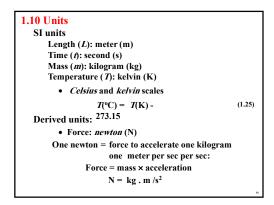


Apply to velocity component <i>u</i> . Set $f = u$ $\frac{du}{dt} = \frac{Du}{Dt} = u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} + w\frac{\partial u}{\partial z} + \frac{\partial u}{\partial t} $ (1.22) (1.22) represents
$u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} + w\frac{\partial u}{\partial z} = \text{ convective acceleration in the x-direction}_{(f)}$
$\frac{\partial u}{\partial t} = \text{local acceleration} \tag{g}$
Cylindrical coordinates : r, θ, z
$\frac{dv_r}{dt} = \frac{Dv_r}{Dt} = v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} + \frac{\partial v_r}{\partial t} $ (1.23a)

$\frac{dv_{\theta}}{dt} = \frac{Dv_{\theta}}{Dt}$	
$= v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} + \frac{\partial v_\theta}{\partial t}$	(1.23b)
$\frac{dv_z}{dt} = \frac{Dv_z}{Dt} = v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} + \frac{\partial v_z}{\partial t}$	(1.23c)
• Total derivative of temperature:	
set <i>f</i> = <i>T</i> in (1.21)	
$\frac{dT}{dt} = \frac{DT}{Dt} = u\frac{\partial T}{\partial x} + v\frac{\partial T}{\partial y} + w\frac{\partial T}{\partial z} + \frac{\partial T}{\partial t}$	(1.24)

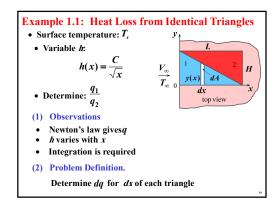
1.9 Problem Solving Format Solve problems in stages:	
(1) Observations	
(2) Problem Definition	
(3) Solution Plan	
(4) Plan Execution	
(i) Assumptions	
(ii) Analysis	
(iii) Computations	
(iv) Checking	
(5) Comments	
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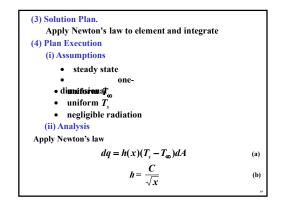


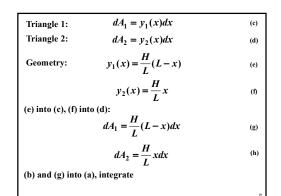
• Energy: joules (J)

One joule = energy due to a force of one newton moving a distance of one meter $J = N. m = kg \cdot m^2 / s^2$

• Power: watts(W) One watt = one joule per second W = J/s = N. m/s = kg . m2 /s3







$$q_{1} = \int dq_{1} = \int_{0}^{L} C(T_{s} - T_{\infty}) \frac{H}{L} \frac{L - x}{x^{1/2}} dx$$

$$q_{1} = (4/3)C(T_{s} - T_{\infty})HL^{1/2} \qquad (i)$$
Similarly
$$q_{2} = \int dq_{2} = \int_{0}^{L} C(T_{s} - T_{\infty}) \frac{H}{L} \frac{x}{x^{1/2}} dx$$

$$q_{2} = (2/3)C(T_{s} - T_{\infty})HL^{1/2} \qquad (j)$$
Ratio of (i) and (j)
$$\frac{q_{1}}{q_{2}} = 2 \qquad (k)$$
(iii) Checking
Dimensional check:
(b) gives units of C: C = W/m^{3/2} - {}^{0}C

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(i) gives units of q_1

 $q_1 = C(W/m^{3/2} \circ C)(T_s - T_{\infty})(\circ C)_{H(m)L}^{1/2}(m^{1/2}) = W$

Qualitative

check: $q_1 > q_2$ because base of 1 is at x = 0 where $h = \infty$.

(5) Comments

- Orientation is important.
- Same area triangles but different q
- Use same approach for other geometries